

Systems engineering for future TMT instrumentation

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Let's Take a Tour of TMT Systems Engineering





Quick Overview of the TMT Design



TMT Facility and Enclosure



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Key Telescope Structure Dimensions





TMT design for Instruments

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Optical Parameter	Description
Optical Configuration	 Ritchey-Chretien Telescope: Hyperbolic primary/secondary mirrors Free of third-order coma and spherical aberration, significant off-axis astigmatism
Field of View	15 arcminute diameter unvignetted20 arcminute diameter unobstructed
Primary Mirror	 30 m diameter F/1, 60 m radius of curvature 492 hexagonal segments, a = 0.72m
Secondary mirror	 Radius of curvature: -6.2m 3.0 m diameter (sized for 15 arcmin FOV)
Tertiary mirror	• Flat (points in alt-az to feed instrument locations), 2.5 m x 3.5 m
Back Focal Distance	16.5 m, 20 m from M3 to focusNasmyth Platform edge is at 16 m
Final Focal Ratio	• F/15
Telescope Focal Surface	 Plate scale is 2.18 mm/arcsec 20 arcminutes = 2.62 m telescope focal plane Radius of curvature = 3.009 m (concave as seen from M3)
Throughput	0.34 to 28 microns, goal 0.31 to 28 microns
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Top Level TMT Image Quality Requirements

Observing Mode	Requirement (short text)	REQ Reference
Seeing Limited	PSS _N [*] ≥ 0.85	REQ-1-OAD-0400
Multi-Conjugate AO	RMS Wavefront = 191 nm over 17" field	REQ-1-ORD-3530
Multiple Object AO	50% Encircled Energy onto 50 mas square pixel	REQ-1-ORD-4320
High Contrast AO	Contrast of 10 ⁻⁸ @ 50 mas (goal 10 ⁻⁹ @ 100 mas)	REQ-1-ORD-4520
Mid Infrared AO	RMS Wavefront of 500 nm over field (goal 300 nm)	REQ-1-ORD-4360

* PSS_N = Normalized Point Source Sensitivity



TMT Key Design Feature: Excellent Filled Aperture Sensitivity TMT requires < 2.5% blockage (spiders), total (with M2) 4.1%



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Nasmyth Platforms Instrument Configuration

- Two large Nasmyth
 Platforms, reconfigurable for new instruments.
- Gravity stable environment
- M3 steers light to instrument locations and maintains optical beam at instrument station as telescope moves in Alt-Az.
- Instrument masses to 50,000 kg, 120,000 kg total per platform.





Multiple Addressable Instruments on Nasmyth Structures

Elevation axis above M1 enables several selectable focal planes

- Articulated M3 quickly addresses all locations
- Low vibration, stable instrument environment

NIRES-B

Nasmyth Structures showing entire early light and planned future instrument suite





Nasmyth Platforms





First Decade Instrument Configuration





LGSF and Laser Asterism

 Laser guide starts are launched from behind the secondary mirror.



Figure: LGSF asterisms supporting different AO modes: **NFIRAOS** (black) 1 on-axis, 5 on a 35 arcsec radius; **MIRAO** (red) 3 on a 70 arcsec radius; **MOAO** (blue) 3 on a 70 arcsec radius, 5 on a 150 arcsec radius; **GLAO** (green) 1 on-axis, 4 on a 510 arcsec radius



- LGSF Initially provides
 NFIRAOS asterism (5 LGS @ 35" radius and 1 @ center)
- Upgradeable to others from 5" to 510" radii



Providing a low vibration environment: Vibration Budget

- AO error budget allocation of 30nm to vibration
 Less than 1 mas tip/tilt
- Place requirements on sources of vibration to meet overall budget
 - Specify requirements on RMS force levels in Newtons
 - After passing through shaping filter
 - Allowing more force at high & low frequencies



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Requirement tem name Number	Sandti vity Reaktion Appreptie Subcomponent Appreptie Subcomponent name Value Reaktion Appreptie Subcomponent estimated 50 (mark) Padtor (fit may mm) imped (nm) Millingbad (nm)	Example budget allocation:
Total	28 A	
On Telescope	3.9 24.7	cryocooling is allowed
[BEQ-3-OAD-3000K] Teles cope structure (STR)	26 9.2 Approximative of the second sec	1 N on telescope
[8EQ-3-0AD-XXXX] M2 System (M2)	Norman 2, 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	in on selescope
[REQ-1-OAD-XXXX] M3 System (M3) [REQ-1-OAD-XXXX] Alignment and Phasing System (APS)	4.3 1.0 0.5 2.2 7.6 1.0 0.0 0.0	
[REQ-1-OAD-XXXX] Engineering Sensors (ESEN)	25.0 10 0.0 0.0	
[BEQ-3-OAD-XXXX] These coperiods (TOS) [BEQ-3-OAD-XXXX] Narrow Field Near Infrared On-Axis AD System (NEIRAGS)	76 10 0.5 3.8 76 10 1.0 7.6	Estimated
[REQ-1-OAD-XXXX] NFIRADS Science Calibration Unit (NSCU)	7.6 1.0 0.0 0.0	LStillateu
[BEQ-1-0AD-XXXX] Laser Guide Star Faoility (LGSF)	0.7 9.5 Top-end 25.0 10 0.1 2.5	
	BTO 7.6 1.0 0.5 3.8 Larent 16.0 1.0 0.5 8.0	contribution to
[REQ-1-OAD-XXXX] Communications and Information	Laser electronics 2.3 10 1.0 2.3 7.6 10 1.0 7.6	
[REQ-3-OAD-XXXX] Instrumentation Cooling (COOL)	1.4 10.7	20pm orror budget
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[RED-3-0AD-X00X] Infrared Imaging Spectrometer (IHIS) [RED-3-0AD-XXXX] Wide Field Optical Spectrometer	7.6 10 0.5 2.9 7.6 10 0.5 3.8	
[REQ-1-0AD-XXXX] IRMS/MOSFIRE (IRMS)	7.6 1.0 0.5 3.8	
First decade Instruments	14 10.7	
Requirement Number	Subsystem Su	bcomponent (nm/N) Estimated sensitivity value (N rms) Estimated subcomponent Subsystem aggrigate subcomponent contribution to AO WFE
	Observatory Total Sensitivity (r	nm/N) 30.0
	Contingency from model	ng 6.7
	On Telescope	
[REQ-1-OAD-1137]	Instrumentation Cooling (COOL)	9.9
	Cryot Refrig	cooling 7.0 1.0 7.0 gerant cooling 7.0 1.0 7.0
[REQ-1-OAD-1138]	Infrared Imaging Spectrometer (IRIS)	7.0 0.5 3.5 3.5
[REQ-1-OAD-1139]	Wide Field Optical Spectrometer (WFOS)	
[KEQ-1-OAD-1140]		7.0 0.5 3.5 3.5
[REDD.AD.JOX01] Adaptive Optics Executive Software (ADESW0) [REDD.AD.JOX02] Instrumentation C exits (CODL) [REDD.AD.JOX02] Instrumentation Software (WFOS) [REDD.AD.JOX02] Instrumentation Software (WFOS) [REDD.AD.JOX02] Wide [REDD.AD.SOX02] Wide [REDD.AD.SOX02] Wide [REDD.AD.SOX02] Wide [REDD.AD.SOX02] Wide [REDD.AD.SOX02] Wide [REDD.AD.SOX02] Wide	Identify locations	
(HR OS) [REQ-3-OAD-XXXX] N as-Infrared MsBi Object Sectrometer (IRMOS) [REQ-3-OAD-XXXX] Planet Formation Instrument (PFI) [REQ-3-OAD-XXXX] Mid-Infrared AO System (MIRAO) [REQ-3-OAD-XXXX] Mid-Infrared Schelle Spectrometer	& sources for each	Allowable force
(MR ES) [REQ-3-0AD-X0XX] Near Infrared Echelle Spectrometer (NR ES-B) [REQ-3-0AD-X0XX] Near Infrared Echelle Spectrometer (NR ES-R)	subsystem	level (in Newtons)
[REQ-3-OAD-XXXX] Wide-field Infrared Camera (WIRC) [REQ-3-OAD-XXXX] Communications and Information	0.7 100 5.0 0.4 0.7 10.0 5.0 0.4	
Systems (CIS) [REQ-3-0AD-XXXX] Common Software (CSW)	0.7 10.0 5.0 0.4	
[REQ-1-0AD-XXXX] D ata Management System (DMS) [REQ-1-0AD-XXXX] Executive Software (ESW) [REQ-1-0AD-XXXX] Science Operations Support Systems	0.7 10.0 5.0 0.4 0.7 10.0 5.0 0.4 0.7 10.0 5.0 0.4	17 072 PEL 01
(SDSS) [REQ-3-0AD-XXXX] D ata Processing System (DPS) [REQ-1-0AD-XXXX] Site Conditions Monitoring System	0.7 10.0 5.0 0.4 0.7 10.0 5.0 0.4	



Telescope Services For Instrumentation

- The following utility services are available to instruments on the Nasmyth platforms:
 - Power (various types, cleanliness, UPS)
 - Variable temperature chilled water/glycol (tracks ambient)
 - Liquid nitrogen (CRYO)
 - CO2 refrigerant cooling (REFR)
 - High purity facility compressed air (FCA)
 - Common Network (CNET)
 - Private Network (PNET)
 - Safety network (SNET)
 - Fire Alarm Services



Requirements Engineering

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Importance of Designing to Requirements

- Requirements engineering enables us to answer the questions:
 - What is planned to be built?
 - Did we build what we planned? (Verification / Validation)
- Requirements are the basis for:
 - Project Planning
 - Risk Management
 - Acceptance Testing
 - Design Trade-offs
 - Managing Change (Change Control)



TMT System Decomposition

 Decomposition defines "System of systems"

Reduce
 complexity by
 subdividing
 whole system
 into individually
 buildable and
 testable
 subsystems

Product
 Breakdown
 Structure of
 Subsystems
 maps to WBS



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Requirements Traceability

SRD

- Requirements directly linked to science capabilities
- Operations Plan
 - Highest Level statement of how TMT will operate

OpsRD

 Requirements that science and technical operations place on observatory design

ORD

Requirements defining the observatory system. This is the engineering interpretation of the SRD.

OAD

- High level (architectural) design of TMT
- Key implementation decisions
- Subsystem definitions (high level requirements)
- Coordination between subsystems (high level interfaces)
- Reflects evolution of design
- Subsystem DRDs
 - Separate requirements documents defining each individual subsystems

ICDs

Interfaces trace to subsystem requirements



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Interface Management

186 Interfaces identified between 32 subsystems in n-squared diagram

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M3	M3 System			X			E)	1	R																											
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COAT	Optical Coating System			X				X	D	D		Х																									
TINS	Test Instruments						>	X		D	L		X																								
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NFIRAOS	Narrow Field Infrared AO System			X			E)					X		D				X			R															
NSCU	NFIRAOS Science Calibration Unit						>	0							X				X			X	Х														
LGSF	Laser Guide Star Facility			X			E)							D				D			D		R													
AOESW	Adaptive Optics Executive Software			X											X				X			X		X	D												
COOL	Instrument Cooling System			X			>	0											X			X				Х											
IRIS	InfraRed Imaging Spectrometer			x			>	8							X				X			D			X	X	X										
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Configuration Control: DOORS Requirements Database

- DOORS = "Dynamic Object Oriented Requirements System"
- Industry standard tool to develop, manage and review requirements data



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Basic Requirements Engineering Rules

- Requirements should be:
 - <u>Uniquely identifiable (numbered)</u>
 - Necessary is the requirement really needed?
 - <u>Verifiable</u> is there a method to check if the requirement is met?
 - <u>Attainable</u> within budget, schedule, available technology
 - <u>Clear</u> Do all stakeholders interpret the requirement the same way?
- <u>Be specific</u>: Avoid ambiguity of terms like "maximize", "successfully", "safely", "user friendly"
- Avoid implementation statements. State what is needed, not how it is to be provided. "How" is the design; don't do the design in the requirements.



Requirement Flow-Down Example: Target Acquisition

Requirements are traceable in a Parent-Child relationship:





Requirement Flow-Down Example Target Acquisition (2/2)

- Considering only the Wide Field Optical Spectrograph requirements, flow-down will include requirements on:
 - Time to read out detectors
 - Time to re-position Wavefront Sensors and Guiders
 - Time to change slit masks or fiber postions
 - Time to reconfigure Atmospheric Dispersion Compensator
 - Time to change gratings
 - Time to change filters
 - Time to move instrument rotator
- Supporting analysis documents are needed to show that the coordination of these activities meets the top level requirement (some activities may be in parallel and some in series, with dependencies on other systems)



Common Reasons Projects Fail: Poor Requirements

Most common reasons for project failure are not technical, but are requirements related. Three main categories:

- Requirements are poorly organized, poorly expressed, weakly related to stakeholders, change too rapidly, are unrealistic or unnecessary.
- Management problems of resources (not enough money, lack of support, lack of planning). Many of these arise from poor requirements control.
- 3. Politics (contributes to 1 and 2)
- Reference: Standish Group Study (*Requirements Engineering*, Hull, Jackson, Dick. 2005)



"Better is the enemy of good" - Voltaire

- Requirements allow us to define a system that is:
 - agreed between stakeholders
 - to be accomplished within the allocated time and budget
- Improvement beyond requirements may be seen by stakeholders as having negative consequences:
 - Needless expenditure or resources
 - Delay of project completion / system availability
- Attempted improvement may fail
 - May have minimal effect on performance due to "subsystem optimization" (see section on Error Budgets)
 - Attempts to improve something may make it worse
 - Mirror polishing for example additional polishing may damage optic
 - Adding a "goal" may diminish core performance Information Restricted Per Cover Page TMT.SEN.PRE.17.072.REL01



Thanks!





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